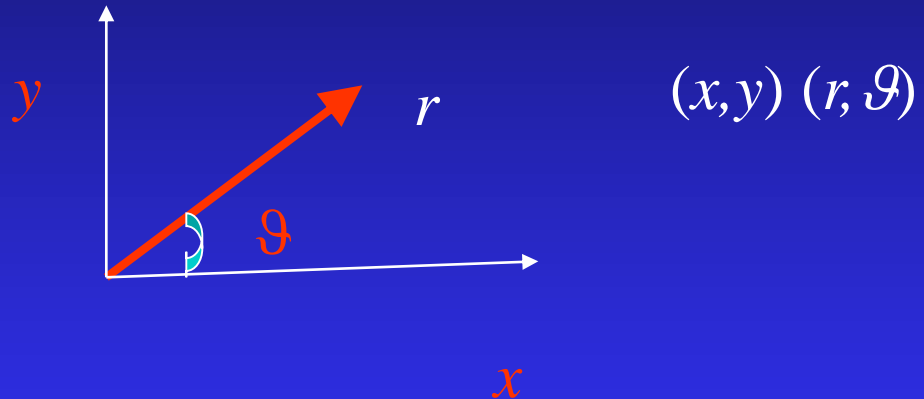


# Chapter 3 Vectors

- Physics deals with many quantities that have both

- Size

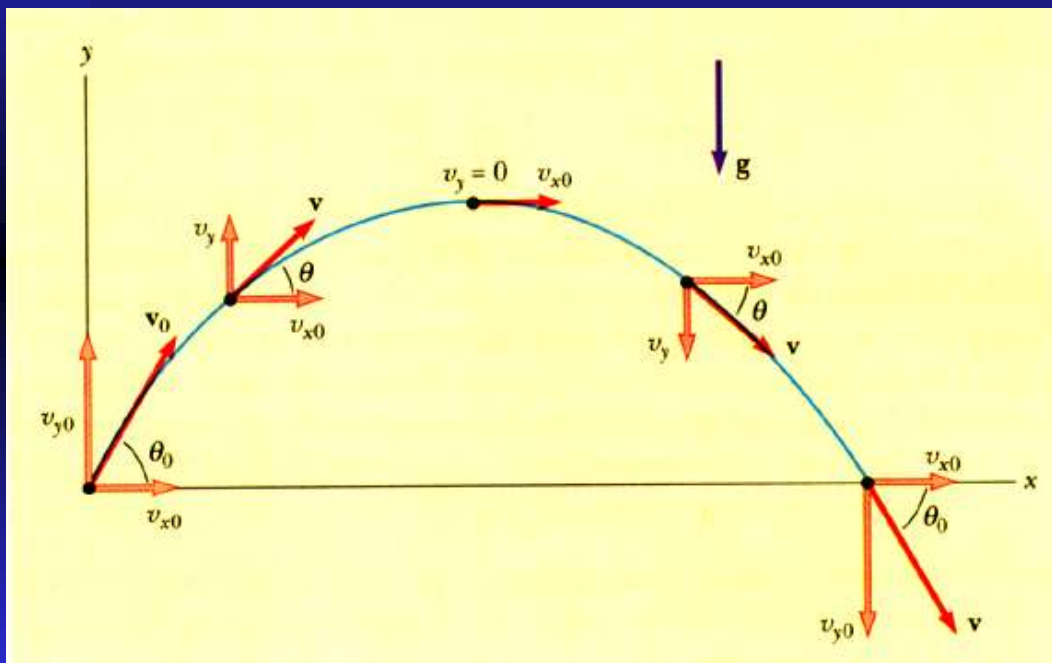
- Direction



- VECTORS !!!!!

- E.g. Displacement, Velocity, Acceleration, Force, Torque

$x$  and  $y$  components of motion are independent-”LINEARITY”



*Componets*

$$v_x = v \cos \theta$$

$$v_y = v \sin \theta$$

$$\vec{v} = (v_x, v_y) = v_x \hat{i} + v_y \hat{j}$$

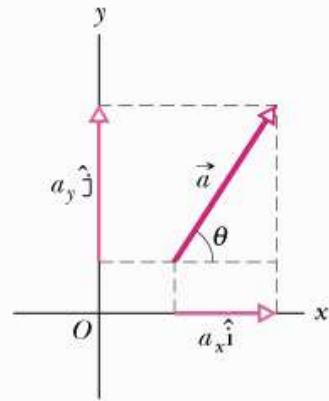
*Unit  
vectors*

# Definitions

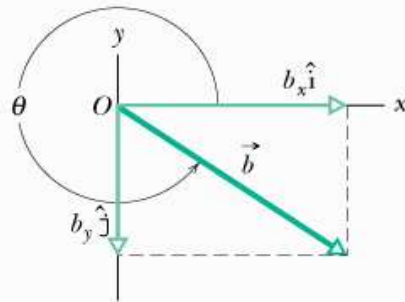
- **SCALAR** provides information about how large a measurement is
  - ◆ Gives one item of information, magnitude, temperature= $T$
- **VECTOR** provides information about how large a measurement is and the direction of the measurement
  - ◆ *Ordered pair numbers required*  $(x, y)$   $(r, \theta)$

# Vectors are added or subtracted according

- ◆ *Ordered pair numbers*  $(x,y)$   $(r, \theta)$

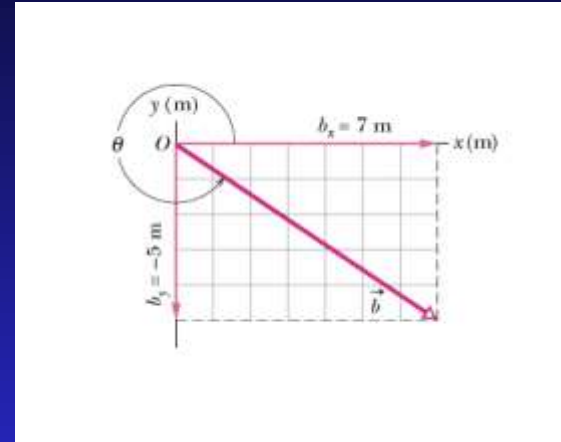
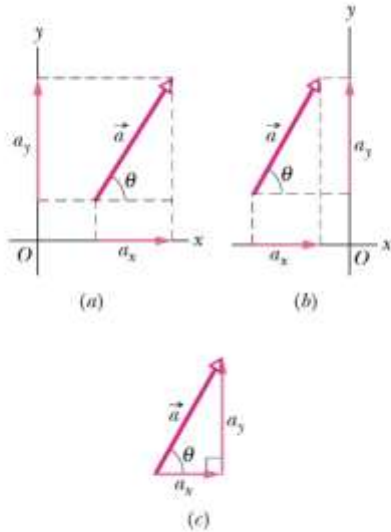


(a)



(b)

# Vector Components

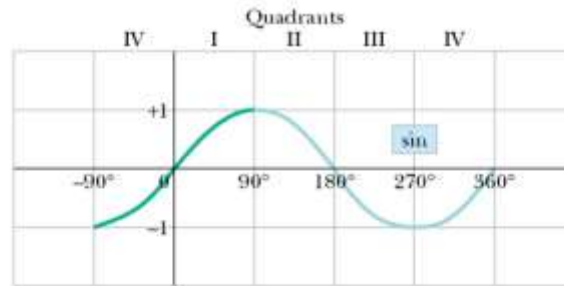


$$\cos \theta = \frac{a_x}{\sqrt{a_x^2 + a_y^2}}$$

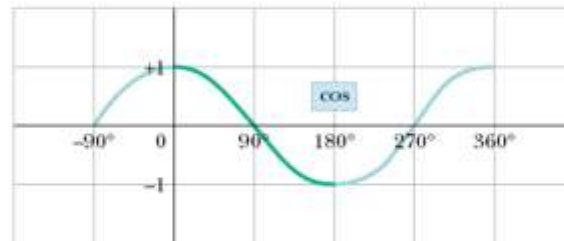
$$\sin \theta = \frac{a_y}{\sqrt{a_x^2 + a_y^2}}$$

$$\tan \theta = \frac{a_y}{a_x}$$

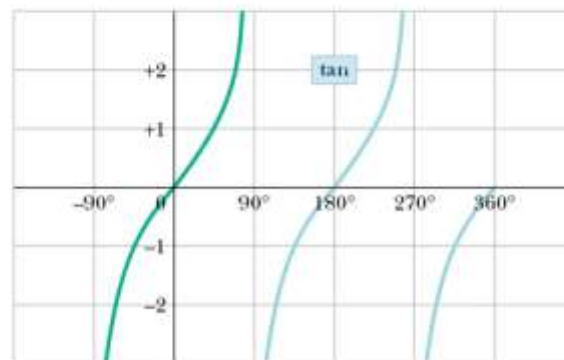
If you use your calculator to determine angle you will find  $\tan^{-1} (-5/7) = -35^\circ \rightarrow 325^\circ$



(a)



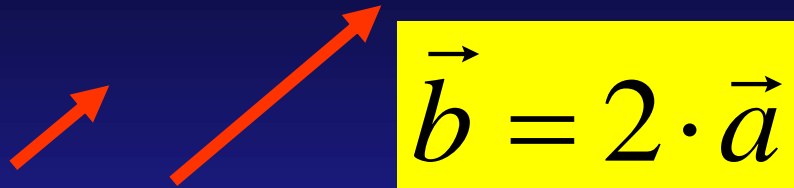
(b)



(c)

# VECTOR ALGEBRA

## ■ Scalar multiplication


$$\vec{b} = 2 \cdot \vec{a}$$

- Vectors are added or subtracted according to the rules for ordered pairs

- **$(a_x, a_y)$ - $(b_x, b_y)$  coordinates!**

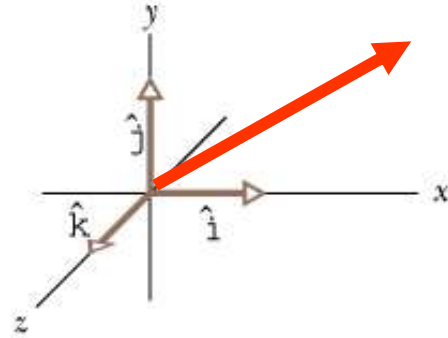
See blackboard

$$\vec{a} = (a_x, a_y) = (4.2, -1.5)$$

$$\vec{a} + \vec{b} = ?$$

$$\vec{b} = (b_x, b_y) = (-1.6, 2.9)$$

# Unit Vector Notation



$$\vec{a} = (4.2, -1.5) \quad \text{or} \quad \vec{a} = 4.2\hat{i} + -1.5\hat{j}$$

$$\vec{b} = (-1.6, 2.9) \quad \text{or} \quad \vec{b} = -1.6\hat{i} + 2.9\hat{j}$$

Unit vectors have magnitude 1 and are “unitless” ... they only give the direction!!!!



# VECTOR NOTATION

- ◆ Components for a vector may be expressed in unit vector notation
  - ◆  $\hat{i}$  is a unit vector in the x direction
  - ◆  $\hat{j}$  is a unit vector in the y direction
  - ◆  $\hat{k}$  is a unit vector in the z direction
- ◆ Bold type or an arrow above the symbol denotes a vector; e.g.,  $\mathbf{A}$  or  $\vec{A}$
- ◆ The magnitude of the above vector is designated  $A$

# VECTOR ALGEBRA cont.

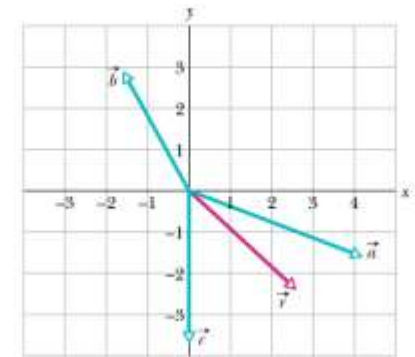
- Vectors are added or subtracted according to the rules for ordered pairs
- $(a_x, a_y) - (b_x, b_y) = (c_x, c_y)$  --coordinates!

$$\vec{a} = 4.2\hat{i} + -1.5\hat{j} \text{ or } (4.2, -1.5)$$

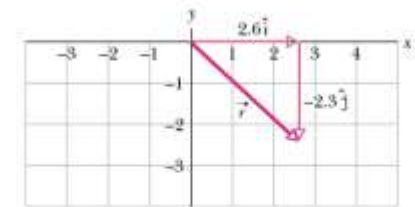
$$\vec{b} = -1.6\hat{i} + 2.9\hat{j} \text{ or } (-1.6, 2.9)$$

$$\vec{c} = 0.0\hat{i} + -3.7\hat{j} \text{ or } (0.0, -3.7)$$

Rule for graphical addition  
is implied!!!!

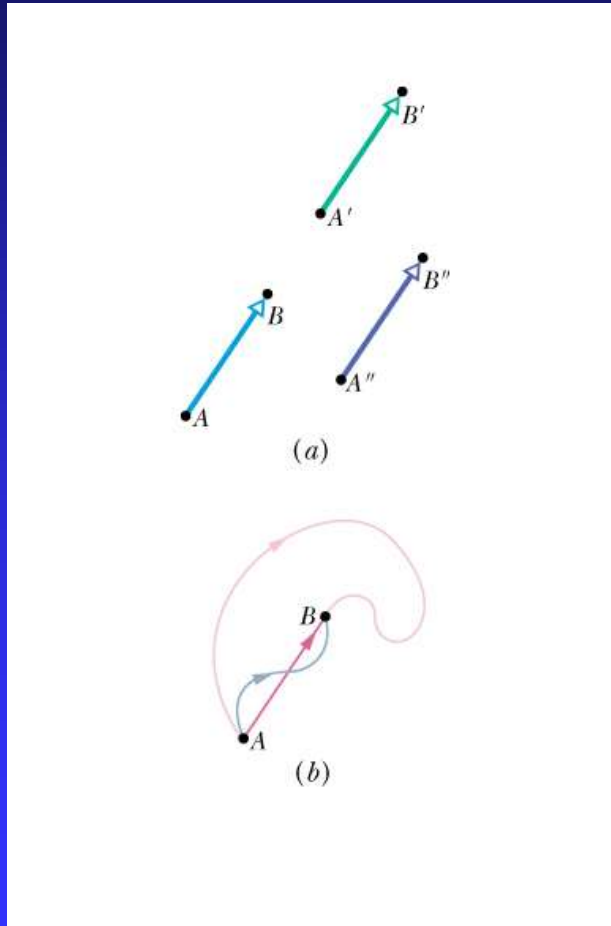


(a)



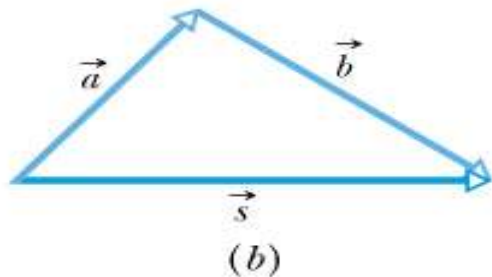
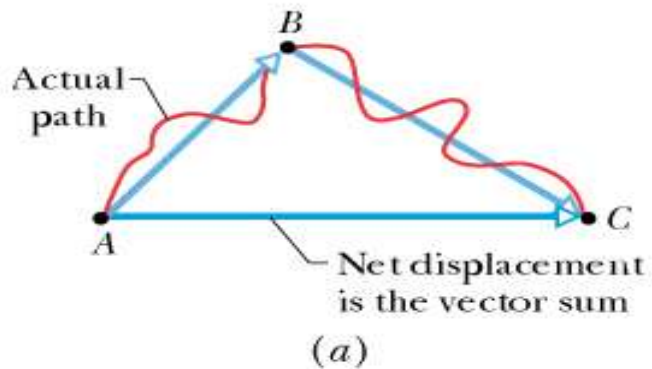
(b)

# Displacement Vector: now in 2-D



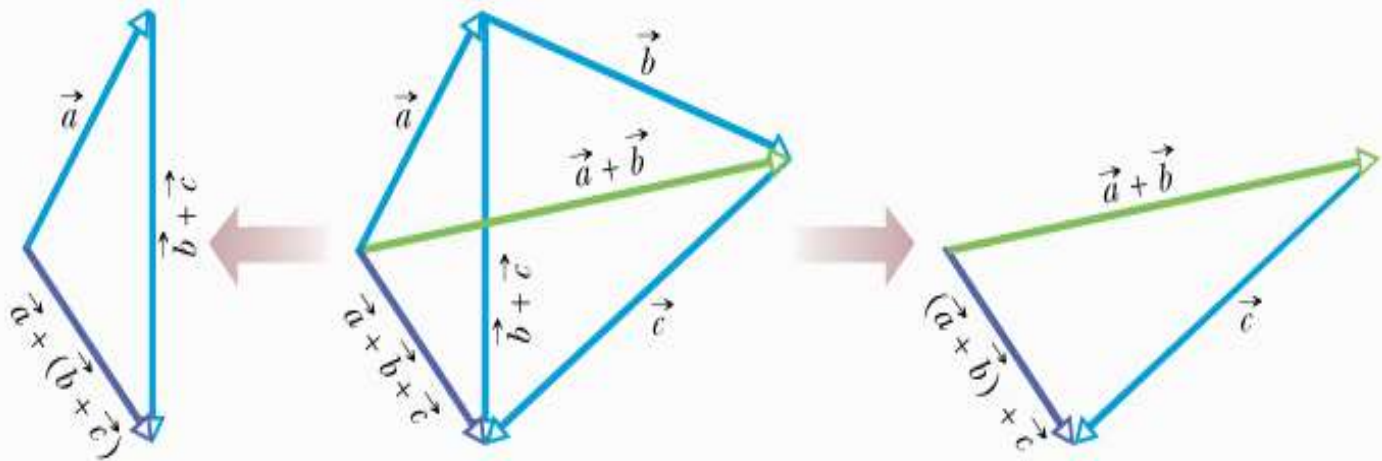
- **Displacement**
- **Three different paths give the same displacement**

# Addition of displacement vectors Graphically



$$\vec{s} = \vec{a} + \vec{b}$$

# Adding more than two vectors graphically

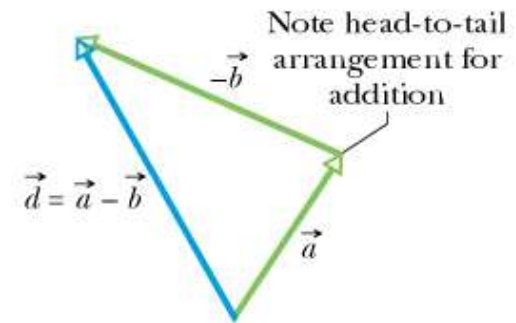
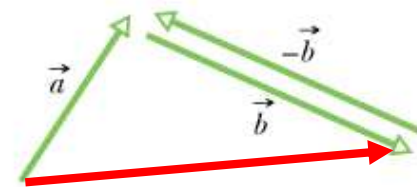
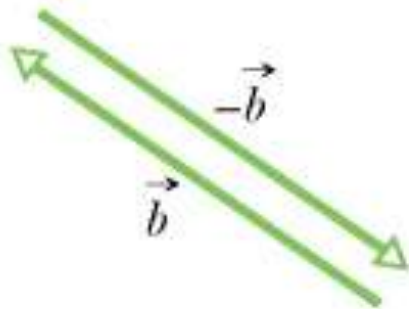


# ADDITIONAL VECTOR PROPERTIES

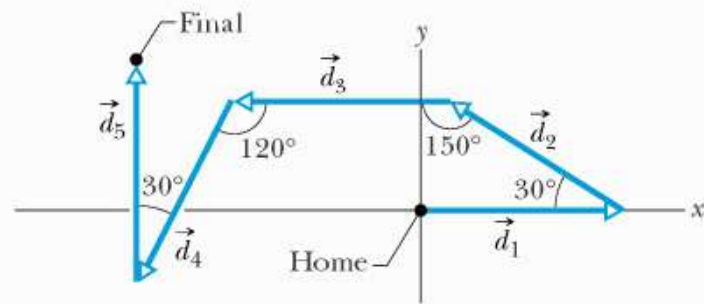
- ◆ A vector can be moved (in a diagram) so long as the magnitude and direction is unchanged
- ◆ Vectors may be expressed as ordered numbers, polar form or in unit vector form
- ◆ Vector subtraction may be accomplished by multiplying the subtracted vector by  $-1$  and using the technique for adding

# Subtraction of Vectors -graphically

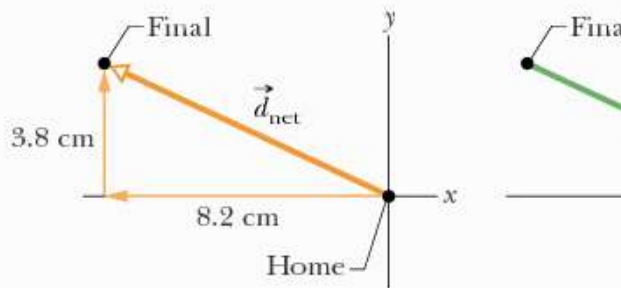
$$\vec{d} = \vec{a} + (-\vec{b}) \text{ whereas } \vec{c} = \vec{a} + \vec{b}$$
$$\vec{d} = \vec{a} - \vec{b}$$



# Ant Example



(a)



(b)

Find resultant  
Find the vector  
home

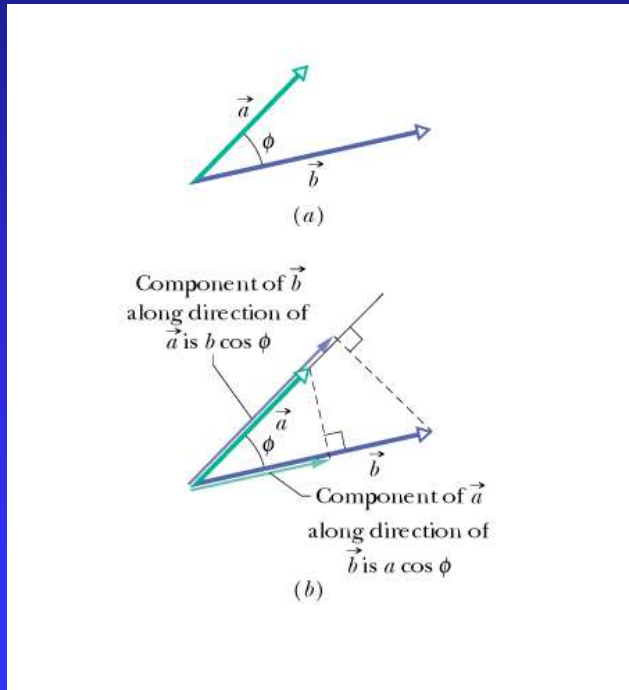


# Vector Multiplication

- Vectors can be multiplied in two ways
  - ◆ A dot product of two vectors results in a scalar  $c = \vec{a} \cdot \vec{b}$
  - ◆ A cross product of two vectors results in another vector  $\vec{c} = \vec{a} \times \vec{b}$
- **Vectors are NEVER divided!**

# The Scalar or Dot Product

- ◆ Multiplication of two vectors resulting in a scalar



$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

Example

$$W = \vec{F} \cdot \vec{d}, \text{ for constant force}$$

# Some Properties of the Dot Product

- Dot products commute

$$\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$$

- The square of a vector

- Unit vector products

$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$$

$$\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{i} \cdot \hat{k} = 0$$

## EXAMPLE 2

What is the dot product of

$$\vec{A} = 5.0 \hat{i} + 3.0 \hat{j}$$

$$\vec{B} = (2.0, 155^\circ)$$

# The VECTOR PRODUCT or CROSS PRODUCT

- Vector multiplication yielding another vector
- Yields a vector which has a direction determined by the **right hand rule**
- Yields a vector **perpendicular to the plane** containing the other two vectors
- The cross product DOES NOT commute

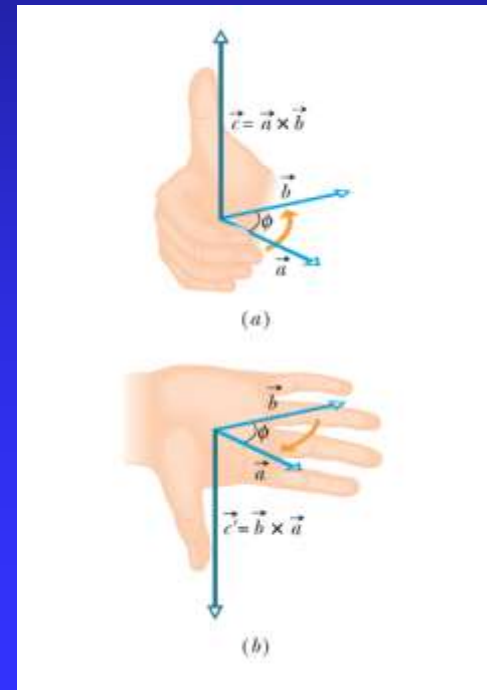
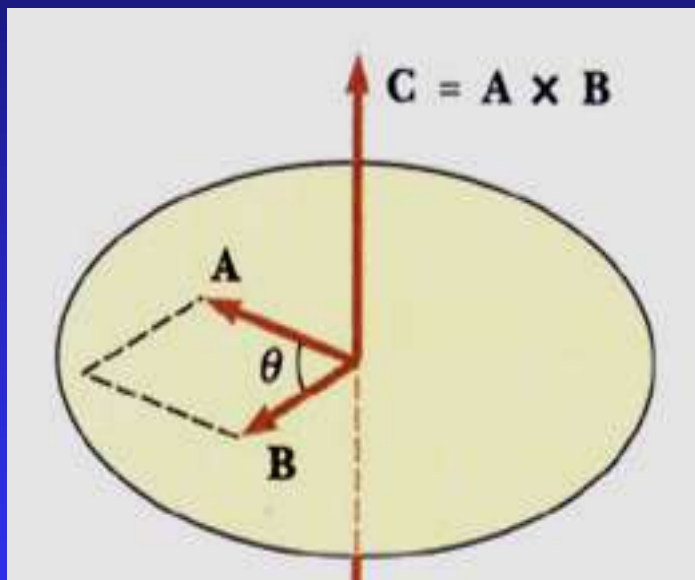
$$\vec{C} = \vec{A} \times \vec{B}$$

$$-\vec{C} = \vec{B} \times \vec{A}$$

$$\vec{\tau} = \vec{r} \times \vec{F} \quad \text{torque}$$

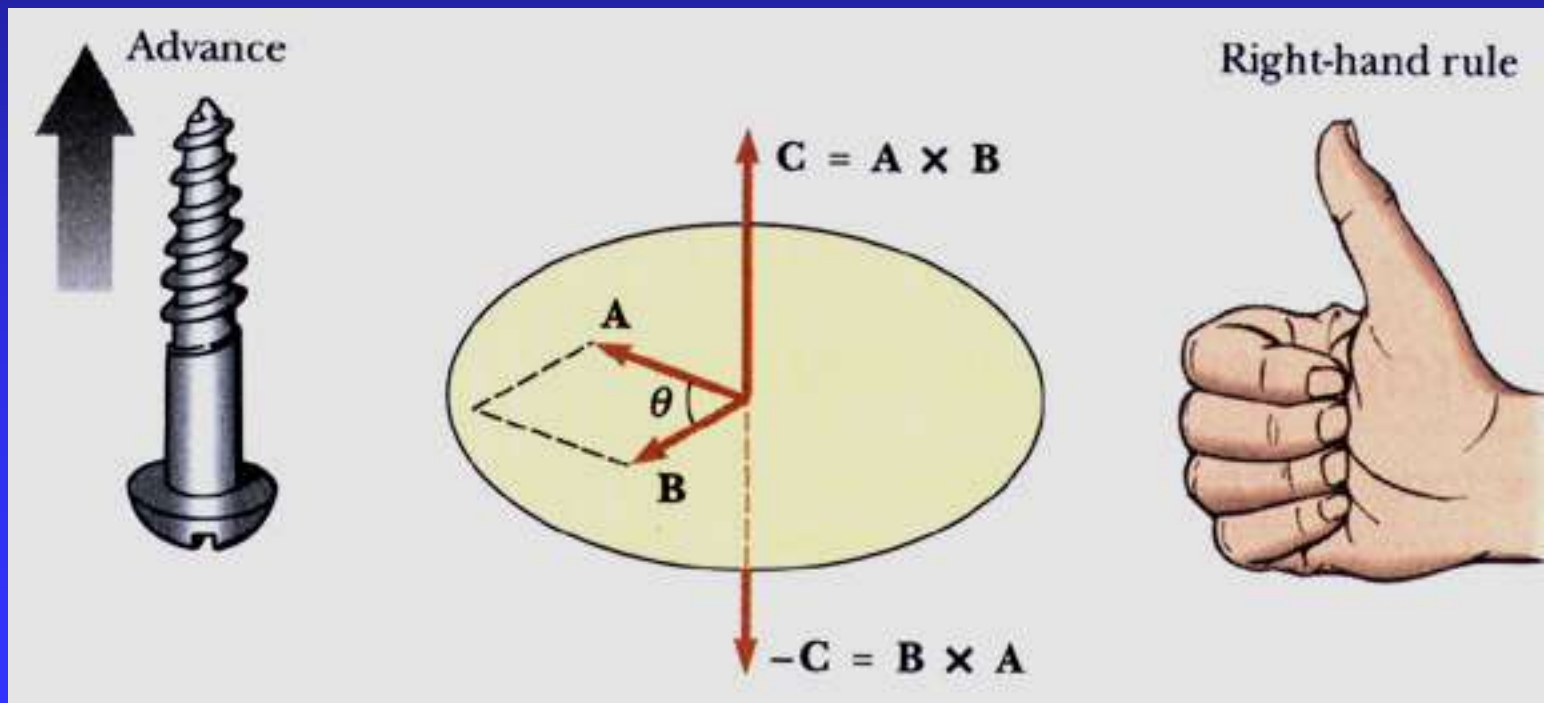
# MAGNITUDE OF THE CROSS PRODUCT

$$C = AB \sin \theta$$



# DIRECTION OF THE CROSS PRODUCT

- The right hand rule determines the direction of the cross product



# Unit Vector Cross Products

- Using the definition of cross product and righthand rule:

$$\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k} = 0$$

$$\hat{i} \times \hat{j} = \hat{k} = -\hat{j} \times \hat{i}$$

$$\hat{j} \times \hat{k} = \hat{i} = -\hat{k} \times \hat{j}$$

$$\hat{k} \times \hat{i} = \hat{j} = -\hat{i} \times \hat{k}$$



## EXAMPLE 3

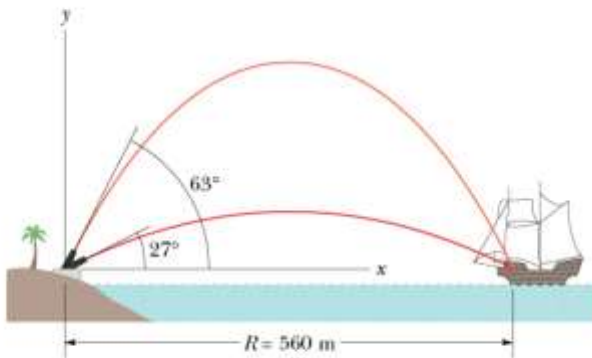
- Calculate the cross product of

$$\vec{A} = 5.00m\hat{i} + 3.00m\hat{j}$$

$$\vec{B} = (2.00m, 155^\circ)$$

# Projectile Motion

- Classic 2-D problem....Eqs. Of Motion?



$$\Delta x \equiv R = \frac{v_0^2 \sin 2\theta}{g}$$